Rapport Bruno Meneses

<https://github.com/BrunoDatoMeneses/Interships/tree/master/M1%20EEA%20ISTR>

Pour faire marcher le code du Baxter il faut inclure le Github “ros\_controllers-hydro-devel” (<https://github.com/RethinkRobotics/baxter_simulator>) dans le repertoire Working\_Folder-Baxter/ros\_ws/src.

Code PL ENSEEIHT 2016 & Code Baxter

<https://github.com/BrunoDatoMeneses/Transport-Network-and-Baxter>

Type of messages link V-Rep/ROS !!

<http://www.coppeliarobotics.com/helpFiles/en/rosSubscriberTypes.htm>

V-Rep list of functions

<http://www.coppeliarobotics.com/helpFiles/en/apiFunctionListCategory.htm>

V-Rep change of color

<http://www.forum.coppeliarobotics.com/viewtopic.php?f=9&t=2493>

<http://www.forum.coppeliarobotics.com/viewtopic.php?f=9&t=2609>